

TRUE ECHO®

CR-L 80GHz FMCW Liquid Level Radar

USER MANUAL



For all CR-L-IS units and for CR-L-GP units
with serial numbers greater than S2606112.

Doc # 9007043
Part # 201318
Rev A, 07/2026

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INTRODUCTION

Thank you for purchasing a TRUE ECHO® CR-L Radar Liquid Level Sensor from APG. We appreciate your business! Please take a few minutes to familiarize yourself with your sensor and this manual.

The TRUE ECHO CR-L radar is a Frequency Modulated Continuous Wave (FMCW) radar operating at 76-81 GHz. It has a maximum measuring range of 49.2 feet (15 m) and a minimum blind zone of 4 inches (0.1 m). The TRUE ECHO CR-L brings the accurate level readings of radar sensors to industrial liquid measurements. It can accurately measure in many adverse environments. Its narrow beam can detect small targets and achieve precise positioning with high resolution. All TRUE ECHO CR-L sensors can be easily setup and field adjusted via the TRUE ECHO app.

READING YOUR LABEL

Every TRUE ECHO sensor comes with a label that includes the instrument's part number, model number, and serial number. Please ensure that the part number on your label matches your order.

KEY FEATURES

- Millimeter wave technology allows higher signal-to-noise ratio and smaller blind zone.
- Minimum 8° antenna beam angle for less side interference and ease of installation.
- Measurement accuracy up to ± 3 mm
- Material dielectric constant ≥ 2
- Integrated design, small size.
- Chemical resistance
- False echo suppression
- 4-20 mA (2 wire), and RS-485 (4 wire) outputs.
- Mobile communication to facilitate on-site personnel maintenance work.
- CSA Intrinsically Safe Class I Div 1, Zone 0 Hazard rating

NOTE: Find product specifications, accessories, and more in the Data Sheet. Go to: <https://apgsensors.com/product/true-echo-cr-l-radar-sensor/>

CERTIFICATIONS

CSA



Class I Div 1 Groups A,B,C,D,T4 Ta=-40°C...70°C

Ex ia IIC T4 Ga, Class I, Zone 0, AEx ia IIC T4 Ga

4-20mA Ui=30Vdc, Ii=130mA, Pi=0.9 W, Ci=12nf, Li=200uH

RS-485 Ui=30Vdc, Ii=300mA, Pi=0.9 W, Ci=12nf, Li=200uH

Optional Type 4/4x*

*Type4/4x is recommended for outdoor use with harsh environmental conditions.

❗ IMPORTANT: CR-L-IS level sensor MUST be installed according to drawing 9007010 (Intrinsically Safe Installation Drawing for Hazardous Locations) in Appendix A to meet listed approvals. Faulty installation will invalidate all safety approvals and ratings.

DANGER: POTENTIAL ELECTROSTATIC CHARGE HAZARD.

AVERTISSEMENT – DANGER POTENTIEL DE CHARGES ELECTROSTATIQUES.

FCC / ISED

FCC ID: VPKAPGTRUEEC80

IC: 7385A-APGCRL

Contains Transmitter Module

FCC ID: 2ABN2-2340B1

IC:23949-2340B1

Please see Appendix B for FCC and ISED warnings.

❗ IMPORTANT: FCC regulations require 75-85 GHz radars to be installed to ensure a vertically downward orientation at fixed locations only. They must not operate while being moved or while inside a moving container. Hand-held applications are prohibited as well as marketing to residential consumers.

WARRANTY AND WARRANTY RESTRICTIONS

This product is covered by APG's warranty to be free from defects in material and workmanship under normal use and service of the product for 24 months. For a full explanation of our Warranty, please visit apgsensors.com/warranty-returns. Contact Technical Support to receive a Return Material Authorization before shipping your product back.

REPAIR AND RETURNS

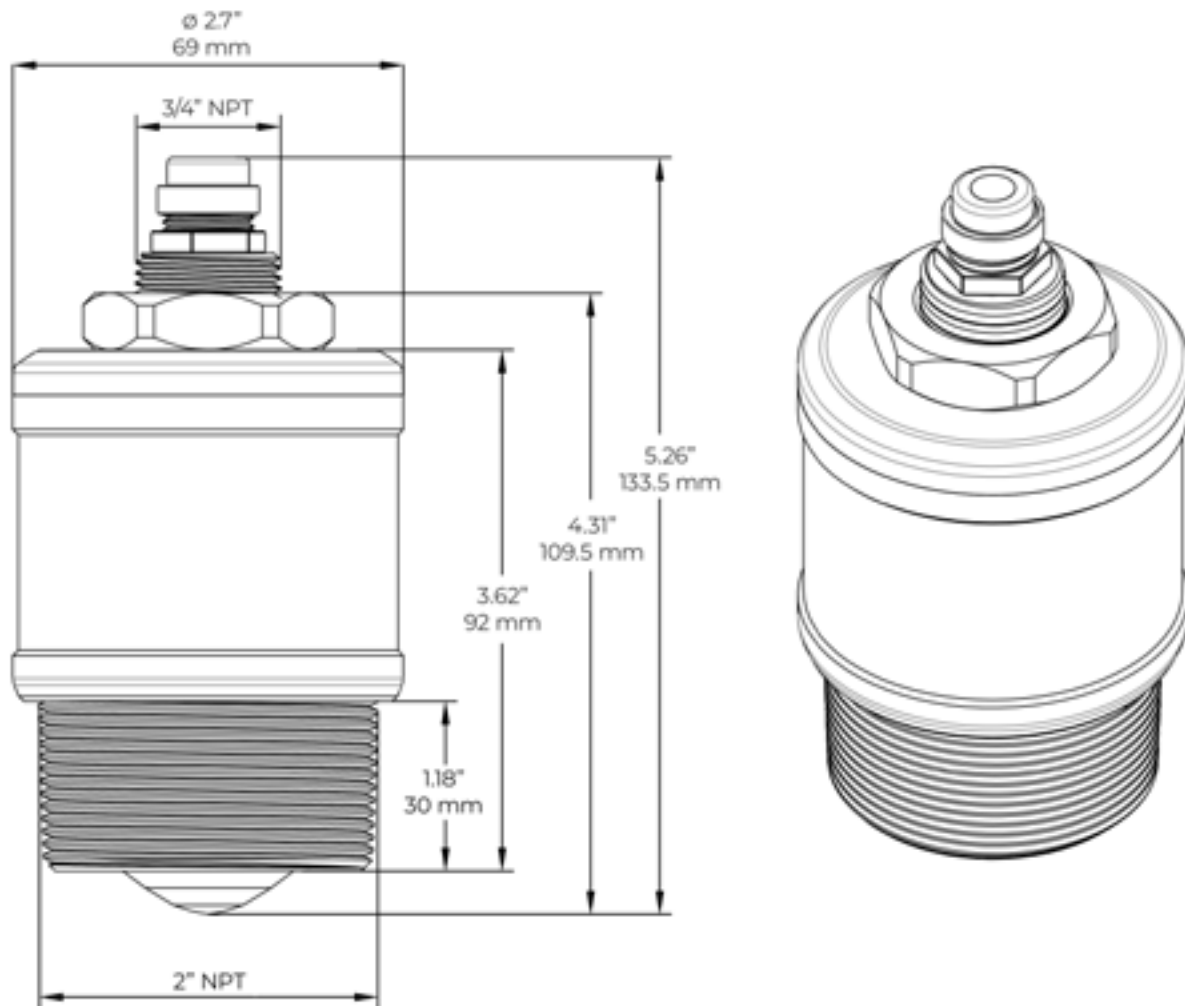
Should your TRUE ECHO Radar require service, please contact the factory via phone, email, or online chat. We will issue you a Return Material Authorization (RMA) number with instructions. You can also find the form on our website by clicking "RMA" in the web footer, or go to apgsensors.com/RMA-Form.

- Phone: 888-525-7300
- Email: sales@apgsensors.com
- Online chat: www.apgsensors.com

Please have your part number and serial number available.

CHAPTER 1: DIMENSIONS AND WIRING

DIMENSIONS



TRUE ECHO CR-L Radar

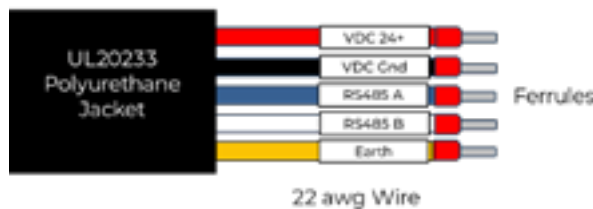
ELECTRICAL PINOUT AND POWER SUPPLY TABLES

PIN OUT TABLES

	4-20 mA
Red	Power Supply + 12 to 28 VDC
Black	4-20 mA Out
Yellow	Shield, Earth Ground



	RS-485
Red	Power Supply + 12 to 28 VDC
Black	Power Supply Ground -
Blue	RS-485 A+
White	RS-485 B-
Yellow	Shield, Earth Ground



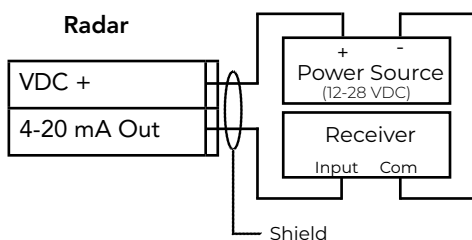
WIRING INFORMATION

POWER SUPPLY TABLE

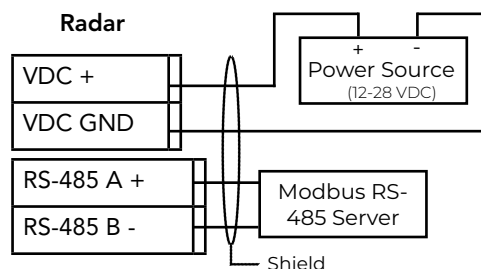
Output	Voltage at Radar	RMS Current
4-20 mA	12 to 28 VDC	4 to 20 mA
RS-485	12 VDC	17 to 32 mA
	24 VDC	10 to 20 mA
	28 VDC	9 to 18 mA

Note: When using barriers with IS radars, the min voltage at the radar must be 12 VDC.

4-20 mA Connection:



RS-485 Connection:



NOTE: Connect Shield wire to Power Supply Earth Ground.

IMPORTANT: CR-L-IS Intrinsically safe sensors MUST be installed according to the Hazardous Installation Drawing drawing 9007010 in Appendix A to meet listed approvals. Faulty installation will invalidate all safety approvals and ratings.

CHAPTER 2: INSTALLATION AND REMOVAL PROCEDURES

PHYSICAL INSTALLATION NOTES

- The material to be measured must have a dielectric constant greater than 2.
- In areas with direct sunlight, it is recommended to install the instrument in a cool place or use a sun visor to avoid excessive temperature and to provide good ventilation and heat dissipation.
- For harsh environments, use Type 4/4x PVDF Housing sensors.
- Mount your TRUE ECHO sensor so that it has a clear, perpendicular path to the surface being monitored.
- Install at least 8 inches from a side wall.
- The radar path should be free from obstructions and as open as possible for the 8° beam pattern. Mount the sensor away from tank or vessel inlets.
- Wrap PTFE tape around threads before installing the radar into the tank opening. This will help it screw in easier. **Do not over tighten.**
- For proper performance and accuracy, do not suspend by cable without the use of the optional weight.
- Be careful not to scratch or damage the radar face.

TOOLS NEEDED

- Tools to make electrical connection
- Mobile device with short-range wireless communication

MOUNTING INSTRUCTIONS

- STEP 1:** Mount the radar using the 2 inch NPT bottom threads or the 3/4 inch NPT top threads and nut. **Do not over tighten.** If suspending the radar by the cable, use the 316SS weight accessory.
- STEP 2:** Attach the wires to your control system according to the information on page 2.
- STEP 3:** Power on the radar. The radar will take the level reading within 6 seconds.
- STEP 4:** Use the TRUE ECHO app to connect to the radar via your mobile device. See “Programming with the App” on page 6 for more information.

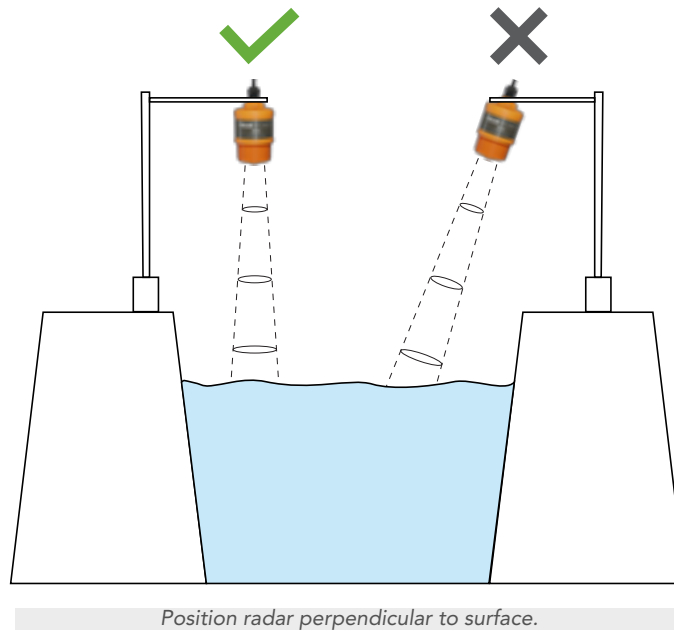
❏ **NOTE:** For information on mounting bracket accessory or weight accessory options, see the CR-L Datasheet. <https://apgsensors.com/product/true-echo-cr-l-radar-sensor/>



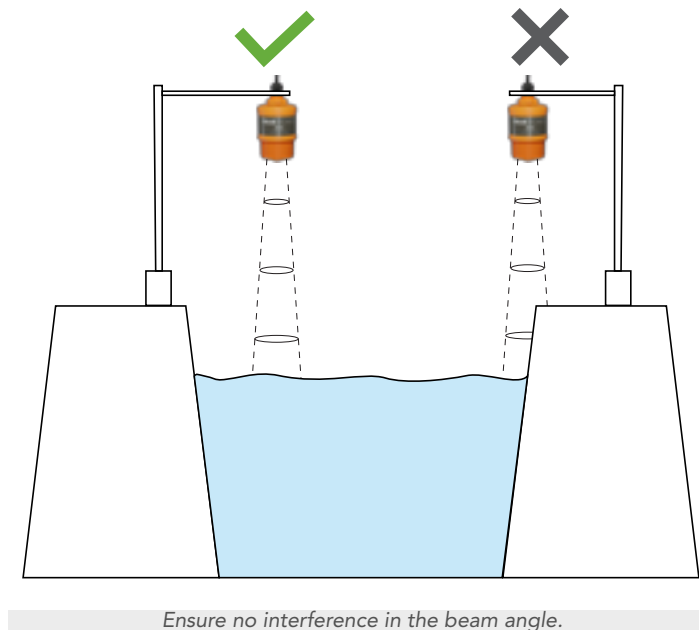
SENSOR PLACEMENT

Ensure the radar level transmitter is installed **perpendicular** to the liquid surface.

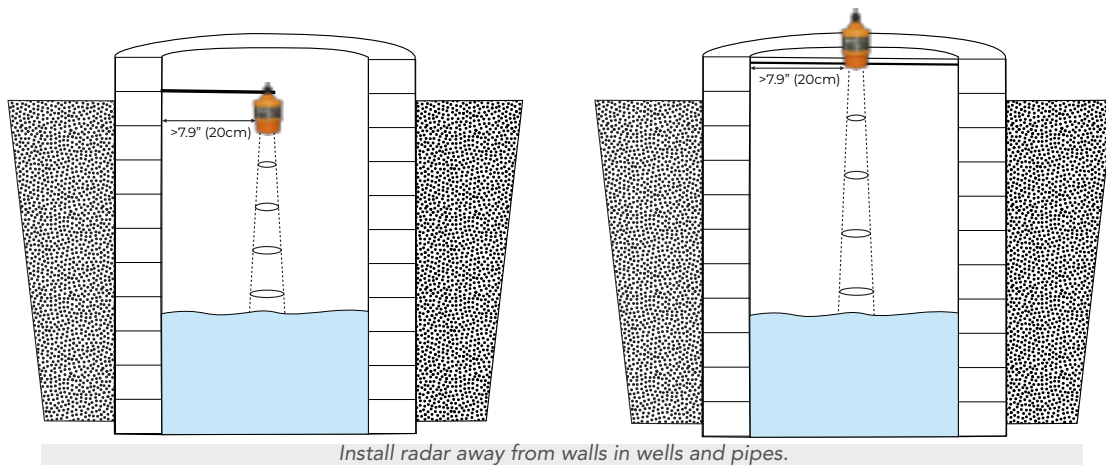
Installing the radar at an angle will weaken the signal amplitude, cause unwanted reflections, and affect the normal range.



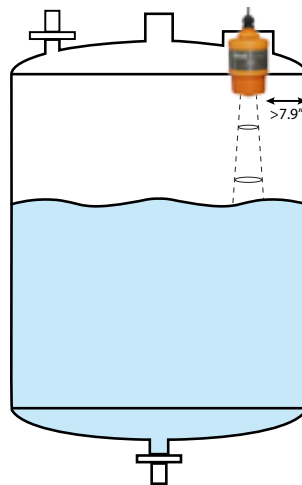
Ensure that there are no obstacles within the beam angle, such as riverbanks, tank walls, ladders, steps, etc.



Install the radar at least 7.9 inch (20 cm) away from side walls. When installing in wells or pipes, place the radar as close to the center as possible to avoid interference from the walls.



When installing in tanks with domed lids, install off center to avoid additional false echoes.



Install radar off center in domed tanks, at least 7.9" away from side walls.

REMOVAL INSTRUCTIONS

Removing your radar from service must be done with care.

- STEP 1:** Ensure power is turned off.
- STEP 2:** Disconnect the radar wires.
- STEP 3:** Remove the radar from its mount.
- STEP 4:** Store it in a dry place, at a temperature between -40° to 158°F (-40° to 70°C).

NOTE: For CR-L-IS radars, please see hazard warnings on page III-IV.

CHAPTER 3: PROGRAMMING WITH THE APP

All TRUE ECHO radar sensors are compatible with our TRUE ECHO app. To change settings and parameters easily with your mobile device, download the free TRUE ECHO Radar App by searching “TRUE ECHO” in the Apple or Google Play Store.



Please ensure your mobile phone or tablet meets the following conditions.

- Operating system: IOS 13 or above
- Operating system: Android 10 or above

CONNECT SHORT-RANGE WIRELESS COMMUNICATION

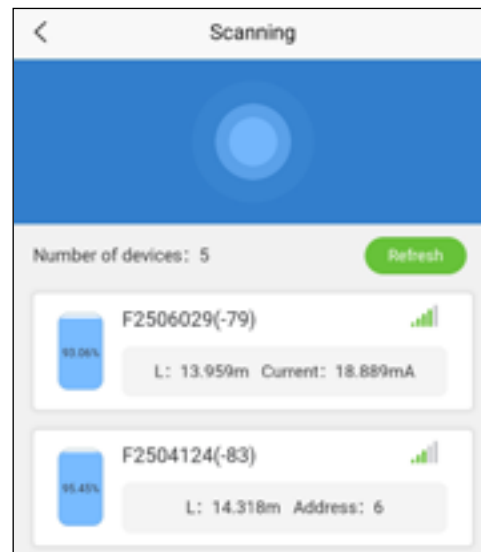
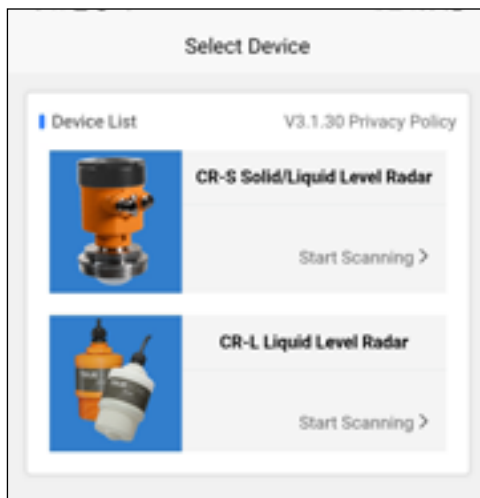
STEP 1: Install the TRUE ECHO app from the app store.

STEP 2: Open the TRUE ECHO app. On the Select Device screen, press “CR-L Liquid Level Radar.”

STEP 3: Each radar’s name or serial number is displayed with either its Level and Current for 4-20 mA units or its Level and Modbus Address for RS-485 units. Press the radar’s name to access it.

STEP 4: Enter the password. The factory default password is **000000**. This can be changed in the app settings. If the changed password is forgotten, please call APG with the serial number on the label for a password reset code.

NOTE: When opening the app for the first time after installation, the app will prompt users to accept the Privacy Policy and will request Location and Relative Position permissions. These permissions are required to connect to the radar.



NOTE: If you don’t see the device on the scanning screen, make sure the radar is wired correctly and powered on. Press “Refresh” to scan for devices.

The message “Reading all Settings” will be seen while the radar parameters are loaded into the app.

Target Information is shown at the top of the screen:

4-20mA App Menu

Config Info			
Distance:	0.48m	Range:	15m
Level:	14.52m	Reliability:	107dB
Current:	19.487mA		

RS-485 App Menu

Config Info			
Distance:	0.6929m	Range:	30m
Level:	29.307m	Reliability:	85dB
485 Address:	1		

- **Distance:** Distance from face of sensor to the target
- **Level:** Range minus Distance
- **Current:** mA based on Level (4-20mA sensors only)
- **Range:** Radar processing distance
- **Reliability:** Signal strength in dB
- **485 Address:** (RS-485 sensors only)

Parameter	Parameter Range	Default
Unit Setting	ft, m, in, cm, mm	m
Range Setting	0 to max sensor range	15 m
High Low Setting	0 to max sensor range	15 m
Damping Setting	0 to 100 s	5 s
Blind Area Setting	0.33 ft (0.1 m) to max sensor range	0.33 ft (0.1 m)
Distance Offset	-0.75 to 3.28 ft (-0.229 to 1 m)	Factory Calibrated
Change Rate	Slow, Medium, Fast, Ultra Fast	Medium
Current Output (mA output only)	Output Mode, Failure Mode	Output Mode: 4-20 Failure Mode: Hold Last Value
Current Simulation (mA output only)	4-20 mA	n/a
Current Calibration (mA output only)	4 mA, 20 mA	n/a
False Echo Learning	Start , End	n/a
False Echo Edit	Start Level dB, End Level dB, Start, End	n/a
Foam / Dust	None, Small, Medium, Large	None
Fluctuation / Angle	None, Small, Medium, Large	None
Filling / Emptying Rate	0 to 196.85 ft/min (60 m/min)	39.4 ft/min (1 m/min)
Diagnosis	Echo Quality Min/Max Echo Intensity Min/ Max Temp Min/Max Distance Min/Max	n/a
Backup/Restore	Factory Reset Mobile Backup/Restore	n/a
Radar Identification	Radar name changeable by user. 9 characters.	Serial Number
RS-485 Settings (RS-485 output only)	485 Address, Baud Rate, Parity Bit, Stop Bit	1, 9600, No Parity, 1 bit

Press “Details” to see settings.

Unit	m
Range	15 m
Low Level	15 m
High Level	0 m
Damping Time	5 s
Blind Zone	0.1 m
Distance offset	0 m
Change Rate	Medium
Foam / Dust	None
Fluctuation / Angle	None
Feed Rate	1 m/min
Discharge Rate	1 m/min
Firmware Version	V2.1.3
Production Date	2026-06-25
Serial Number	S2606088

SETTING DESCRIPTIONS

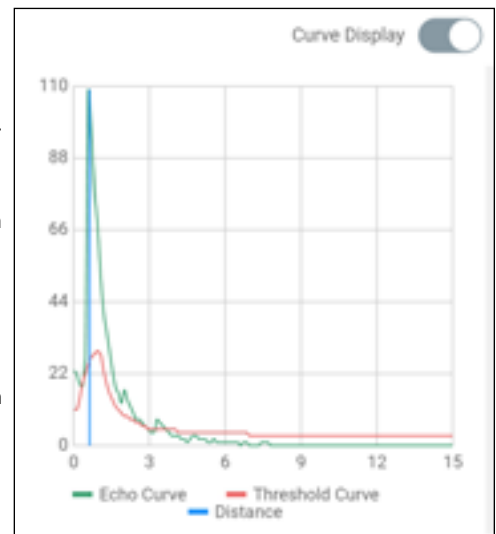
CURVE DISPLAY

Used to view the Echo Curve Graph. This is a visual representation of the echoes the radar is sensing from the target.

The vertical axis is the echo strength in dBs. The horizontal axis is the distance range in the selected unit starting at the sensor face at 0.

The green line is the echo curve and the red line is the threshold curve. The blue vertical line is the distance location of the current reading.

Use the *Curve Display* to validate the radar is sensing the target correctly during installation and setup.



NOTE: Press "Read" to view the current settings in each tab. Press "Write" to save changes.

UNIT SETTING

Used to select the displayed units in the app.

Options:

- mm (millimeters)
- cm (centimeters)
- m (meters) (default)
- in (inch)
- ft (feet)

RANGE SETTING

Used to set the maximum distance the sensor will look for a target measured from the sensor zero reference point. Typically, *Range* is set at or a little beyond the desired measuring range to achieve a fast and stable measurement and avoid false echoes.

- Range: 0.33 to 49.21 ft (0.1 to 15 m)
- Default: 49.213 ft (15 m)

HIGH AND LOW SETTING

Low Level is used to set the **furthest** distance to be measured from the sensor zero reference point to the lowest point of the tank. **Low Level** must be less than or equal to the sensor **Range**. For 4-20 mA sensors, the **Low Level** will define either the 4 mA or 20 mA point (determined by **Current Output Mode** setting).

- Range: 0.33 to 49.21 ft (0.1 to 15 m)
- Default: 49.21 ft (15 m)

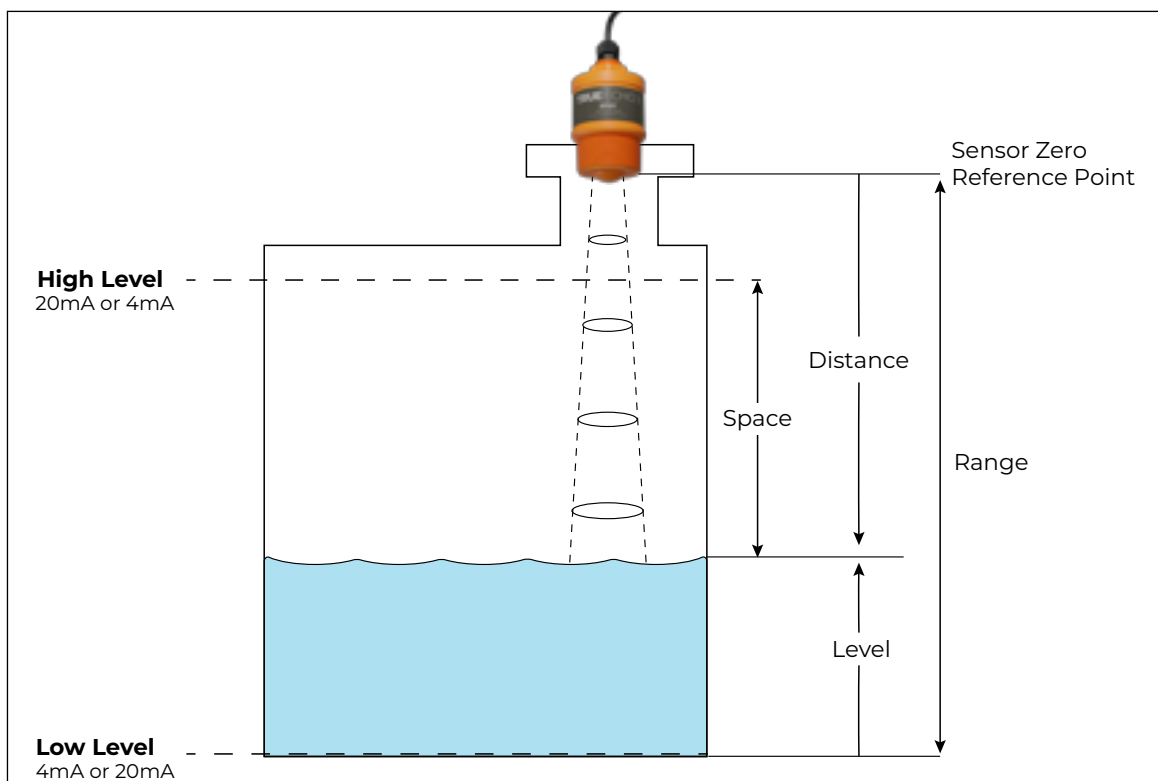
High and Low Setting

*Low Level	15 m
*High Level	0 m

Read Write

High Level is used to set the **closest** point to be measured from the sensor zero reference point to the max fill point in the tank. The **High Level** value must be less than the **Low Level** value. For 4-20 mA sensors, the **High Level** will define either the 20 mA or 4 mA point (determined by the **Current Output Mode** setting).

- Range: 0 to 49.21 ft (0 to 15 m)
- Default: 0



DAMPING SETTING

Used to set the time that is applied to a filter used to smooth sudden changes in the liquid level. A longer *Damping* time will provide more smoothing. A shorter *Damping* time will provide a quicker response with less stability in agitated conditions that may be undesirable.

- Range: 0 to 100 seconds
- Default: 5 seconds

If Damping is greater than 0 the following damping filter is applied:

$$D_{t+1} = \left[D_t + \frac{(D_{target} - D_t)}{k} \right]$$

Where... D_{t+1} = Distance at the next second

D_t = Current distance

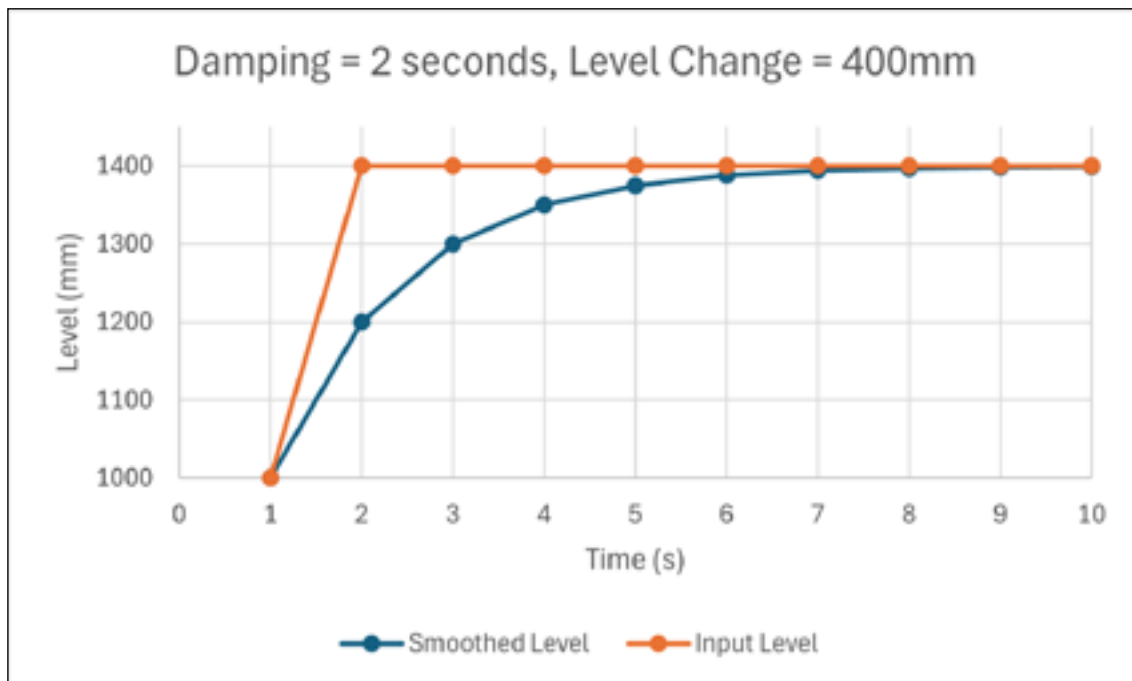
D_{target} = Target distance (distance without damping)

k = Damping factor

In other words:

New Damped Level = Current Damped Level + ((Current Level - Current Damped Level)/Damping)

The following graph shows the smoothing applied with the *Damping* = 2.



BLIND AREA SETTING

Used to define the distance in front of the sensor where it will not look for a valid target. Typically, it is set a little less than the closest liquid level to achieve a fast and stable measurement.

- Range: 0.33 to 49.213 ft (0.1 to 15 m)
- Default: 0.33 ft (0.1 m)

NOTE: The Blind Area and Range determine the processing bounds of the application. They should be set to avoid interference and false echoes and to achieve a fast and stable measurement.

DISTANCE OFFSET

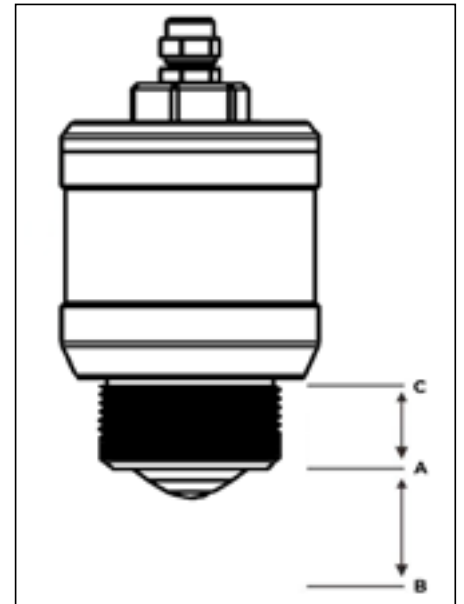
Used to change the position of the zero reference point of the sensor to be at the bottom of the NPT threads as indicated by point A in the figure to the right. It can also be used to offset the sensor reference point as needed.

- Range: ± 0.98 ft (0.3 m)
- Default: Calibrated at factory

To adjust the reference point to point **B**, enter the distance between points **A** and **B** as a negative value. If **A** is -0.197 ft and the desired reference point **B** is 1 foot in front of the sensor face, enter -1.197 ft.

To adjust the reference point to point **C**, enter the distance between points **A** and **C** as a positive value. If **A** is -0.197 ft and the desired reference point **C** is 1 foot behind the face, enter 0.803 ft.

Note: Some digital keyboards do not include a minus (-) key. A different digital keyboard may be needed to enter negative values.



FILLING/EMPTYING RATE

Used to adjust the response rate for tracking the actual liquid level change rate. Set it a little faster than the actual filling and emptying rate.

- Range: 0.033 to 0.66 ft/s (0.01 to 0.2 m/s)
- Default: 0.33 ft/s (0.1 m/s)

CHANGE RATE

Used to set the measurement speed and damping for the fill and empty rate of the material being measured. It is particularly important when the liquid in the tank is under agitation or when material interferes with the radar beam during the filling process. The Change Rate will also affect the time from power on to valid first reading.

Options: Low, Medium, Fast, Ultra Fast

Default: Medium

Change Rate	Filling Speed	Emptying Speed	Damping	4-20 mA Power on to valid data	RS-485 Power on to valid data	Description
Low	1.64 ft/min (0.5 m/min)	1.64 ft/min (0.5 m/min)	10 s	24 s	24 s	Suitable for slow material in/out applications where measurement stability is required
Medium	3.28 ft/min (1 m/min)	3.28 ft/min (1 m/min)	5 s	11 s	11 s	Suitable for most general applications
Fast	6.56 ft/min (2 m/min)	6.56 ft/min (2 m/min)	2 s	5 s	5 s	Suitable for applications requiring fast response
Ultra Fast	32.8 ft/min (10 m/min)	32.8 ft/min (10 m/min)	1 s	3 s	3 s	Suitable for applications requiring ultra-fast response, such as hoppers and anti-collision scenarios

CURRENT OUTPUT (4-20MA OUTPUT ONLY)

Output Mode is used to define the mA values at the Low and High level settings.

Options:

- 4 mA low to 20 mA high (default)
- 20 mA low to 4 mA high

Failure Mode is used to define the output level when a loss of echo or a fault occurs.

Options:

- 3.8 mA
- 4 mA
- 20 mA
- 20.2 mA
- Hold Last Value (default)

CURRENT SIMULATION (4-20MA OUTPUT ONLY)

Used to temporarily output a specific mA value for system testing. The output will return to a normal level when Current Simulation is pressed again to close the option.

Example: If the output is 4.010 mA but should be 4.000 mA, it can be corrected as follows: Press the "4 mA" button. Enter the incorrect value (4.010) and press "Set." The output will change to 4.000 mA.

Range: 4 mA to 20 mA

Resolution: 0.001 mA

CURRENT CALIBRATION (4-20mA OUTPUT ONLY)

Used to calibrate the 4 mA and 20 mA current for system tuning.

Example: If the output is 4.010 mA but should be 4.000 mA, it can be corrected as follows: Press the "4 mA" button. Enter the incorrect value (4.010) and press "Set." The output will change to 4.000 mA.

Options: 4 mA, 20 mA

Resolution: 0.001 mA

FALSE ECHO LEARNING

Used to mask out known obstacles in the measuring range. In practical applications, internal tank structures may generate reflected echoes, called false echoes, that interfere with recognition of the real level echo. To ensure normal measurement, these false echoes should be masked and suppressed by defining their position on the echo curve.

After setting the starting and ending distance values the radar will establish the shielding zone based on the current statistical background noise of the echo signals in this area. Multiple masks can be added.

Options: Add, Clear

Range: 0 to max sensor range

❗ IMPORTANT: The learning area must not cover the real target.

Example using "Add"

Mask out an obstacle 3 meters from the sensor face. The mask START point will be set to 2 m and the mask END point will be set to 4 m.

Enter: Start = 2, End = 4

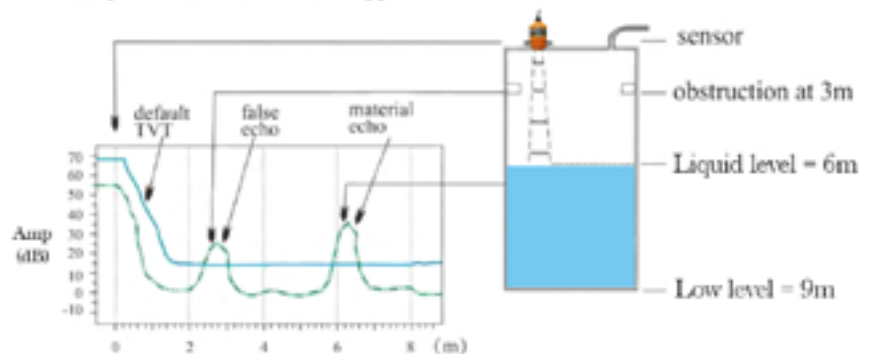
Press: "Add" to enter mask

To clear the mask:

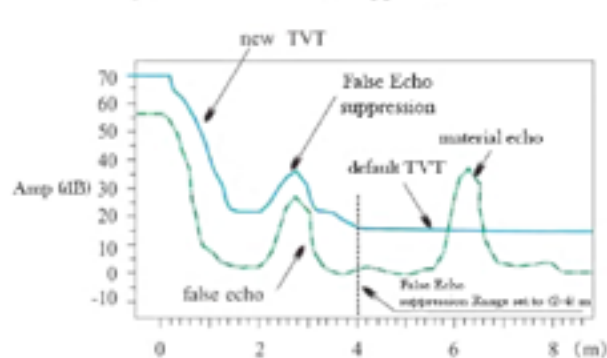
Enter: Start = 2, End = 4

Press: "Clear" to clear mask

Example before False Echo Suppression



Example after False Echo Suppression



FALSE ECHO EDIT

Used to define custom masks with both the shape and the position of the masks. Multiple masks can be added.

Options: Edit, Clear

Range: 0 to max sensor range.

Example using "Edit"

Mask out the echo from 2 to 4 m and set a level dB of 80.

Enter: Start = 2, End = 4, dB = 80

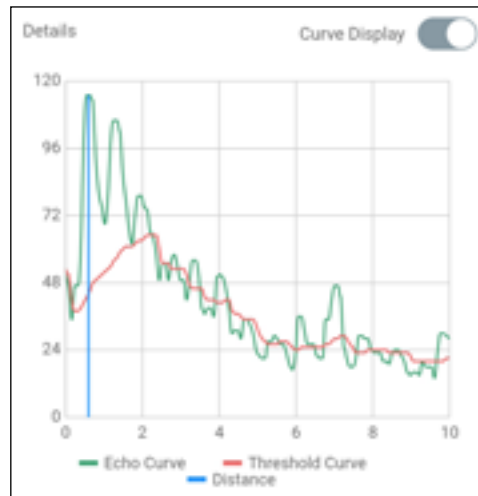
Press: "Edit" to enter mask

To clear the mask:

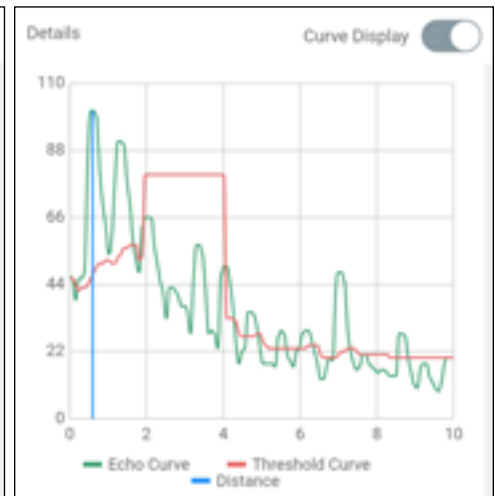
Enter: Start = 2, End = 4, dB = 80

Press: "Clear" to enter mask

- To clear all masks: Set Start = 0 and End = Range setting.



No False Echo Mask



False Echo Mask

FOAM/DUST

Used to adjust the measurement algorithm for foam and dust. Test different settings to optimize the measurement.

- For liquid mediums: Adjust this parameter if a light foam layer is present on the surface of the liquid in the tank. The thickness of the foam can significantly affect the accuracy and stability of radar measurement.
- For solid mediums: Adjust this parameter if a large amount of dust, airborne dust, or vapor is inside the solid material tank.

Options: None, Small, Medium, Large

Default: None

FLUCTUATION / ANGLE

Used to adjust the measurement algorithm for specific conditions in liquids and solids. This adjustment is especially recommended for applications involving high-viscosity solids, granular materials, or stone-like materials. Test different settings to optimize the measurement.

- For liquid media: If the surface of the liquid in the tank fluctuates significantly (e.g. boiling liquid, vortex, or turbulent conditions), this parameter should be enabled
- For solid media: When the solid material in the tank forms a large inclination, such as a heap angle or concave surface, during filling or emptying, this parameter should be enabled.

Options: None, Small, Medium, Large

Default: None

FILLING / EMPTYING RATE

Used to manually adjust the response rate for tracking the actual liquid level and discharge rate. Updates to the Change Rate setting will overwrite the values entered here.

Options: Feed Rate, Discharge Rate

Range: 0 to 196.85 ft/min (60 m/min)

Change Rate	Feed Rate	Discharge Rate	Description
Low	0.5 m/min	0.5 m/min	Suitable for slow material in/out applications where measurement stability is required
Medium	1 m/min	1 m/min	Suitable for most general applications
Fast	2 m/min	2 m/min	Suitable for applications requiring fast response
Ultra Fast	10 m/min	10 m/min	Suitable for applications requiring ultra-fast response, such as hoppers and anti-collision scenarios

DIAGNOSIS

Used to show the max/min values of the following parameters since power on:

- **Echo Quality Max/Min:** Records the highest and lowest echo quality values since power-up. Echo quality refers to the difference between the peak echo intensity minus the TVT curve (signal to noise).
- **Echo Intensity Max/Min:** Records the highest and lowest echo strength values since power-up.
- **Temp Max/Min:** Records the highest and lowest internal temperature measured by the core temperature sensor since power-up. The internal temperature to ambient temperature margin is +/- 2 °C.
- **Distance Max/Min:** Records the highest and lowest measured distance values since power-up.

BACKUP / RESTORE

Factory Reset:

Used to reset settings back to the factory defaults. The app will automatically close. Reopen the app to see the default settings.

Mobile Backup / Restore:

Used to backup settings to the phone. The settings can be restored to other radars.

STEP 1. While the radar is connected to the TRUE ECHO App, set the parameters to the desired values.

STEP 2. Press "Mobile Backup." The settings are now saved to the phone's local storage.

STEP 3. Press "Mobile Restore" to restore the settings back to the radar at any time.

To copy settings to other radars:

STEP 4. Disconnect app communications from the first radar. Use the app to connect to a second radar.

STEP 5. Press "Mobile Restore." The settings are now saved to the radar.

The following settings are affected by the Factory Reset and Backup / Restore commands:

- Unit Setting
- Range Setting
- High Low Setting
- Damping Setting
- Blind Area Setting
- Distance Offset
- Change Rate
- Current Output
- False Echo Learning
- False Echo Edit
- Foam / Dust
- Fluctuation / Angle
- Filling / Emptying Rate

RADAR IDENTIFICATION

Radar App Name allows the 9-character App radar name to be changed. Exit and re-enter the app to see the modified name in the app. The radar Password must be entered to make this change.

Radar Password allows the 6-digit password to be changed from the factory default password (000000). The new password will be required the next time the app is opened. Entering an incorrect password will close the app.

 **NOTE:** If the radar password is forgotten, contact APG for help. Please have the unit's serial number available.

RS-485 SPECIFIC OPTIONS

485 SETTING

Using short-range wireless communication to change the RS-485 settings simplifies installation as units do not have to be isolated to change the Bus Address, Baud Rate, Parity Bit, and Stop Bit settings. See Chapter 4: Modbus Programming for more information about RS-485 programming.

485 Address, also known as Bus Address.

- Options: Address 1 to 247
- Default: Address 1

Baud Rate:

- Options: 1200, 2400, 4800, 9600, 14400, 19200, 38400, 56000, 115200, 156000, 460800, 500000, 51200, 600000, 750000, 921600, 1000000, 1500000, 2000000
- Default: 9600

Parity Bit:

- Options: No Parity, Odd Parity, Even Parity
- Default: No Parity

Stop Bit:

- Options: 1 bit, 1.5 bits, 2 bits
- Default: 1 bit

CHAPTER 4: MODBUS PROGRAMMING

RS-485 (4-WIRE) UNITS ONLY

TRUE ECHO Radar sensors use standard RS-485 Modbus RTU protocol. The sensors can only operate as server devices. Sensor default transmission settings are 9600 Baud, 8 Bits, 1 Stop Bit, No Parity, and require a minimum delay of 100 ms between transactions. The default bus address is 1. The bus address can be changed using the keypad or the TRUE ECHO app.

Modbus communication may override app communication. Using both simultaneously may result in slower app response times.

READ INPUT REGISTERS

Parameter	Function Code	Register Address	Decimal	Quantity	CRC	Type
Space, cm	0x03	0000	0	0001	840A	Uint, 16
Space, mm	0x03	0001	1	0001	D5CA	Uint, 16
Level, cm	0x03	0002	2	0001	25CA	Uint, 16
Level, mm	0x03	0003	3	0001	740A	Uint, 16
Distance, m	0x04	9015	36885	0002	4D0F	Float 32, CDAB
Space, m	0x04	9022	36898	0002	FCC1	Float 32, CDAB
Level, m	0x04	9026	36902	0002	BD00	Float 32, CDAB

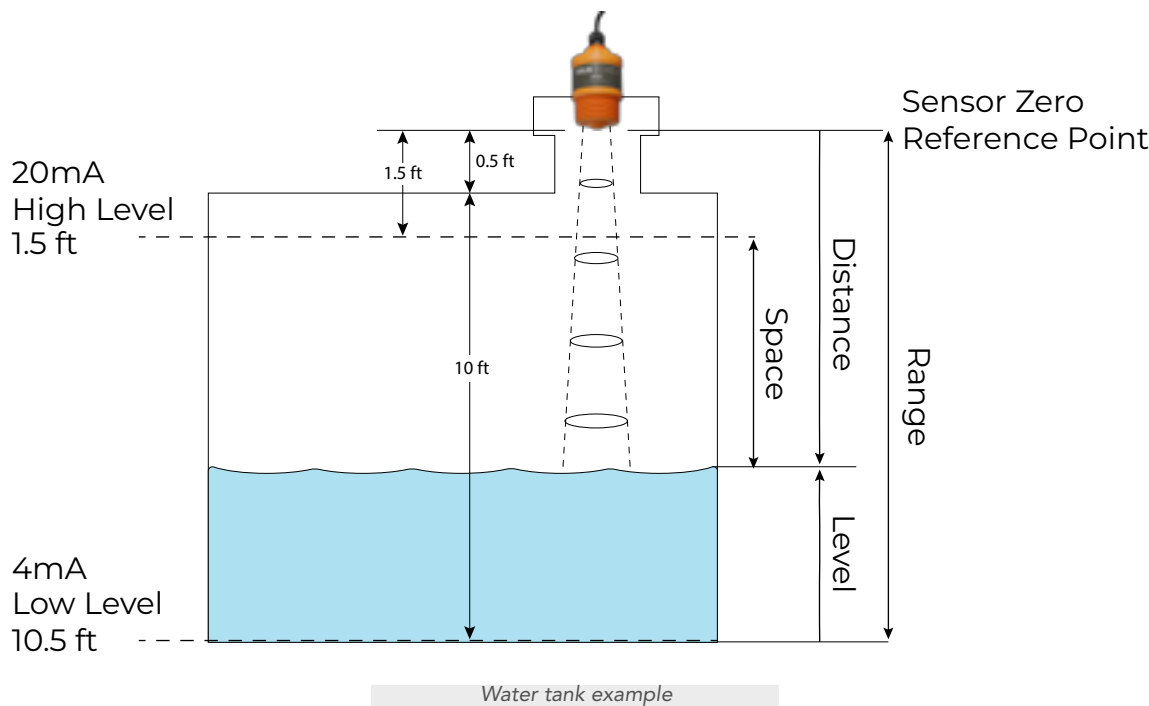
READ HOLDING REGISTERS

For explanations about specific settings, go to Chapter 5: Mobile App Programming.

Parameter	Function Code	Register	Decimal	Data Type
Change Rate Speed 0-3: Low, Medium, Fast, Ultra-Fast	0x03, 0x10	0x9305	37637	uint16
Damping, s	0x03, 0x10	0x930B	37643	uint16
Blind Zone Setting, m	0x03, 0x10	0x9344	37700	Float32, CDAB
Range Setting, m	0x03, 0x10	0x9346	37702	Float32, CDAB
Low Level Setting, m	0x03, 0x10	0x9348	37704	Float32, CDAB
High Level Setting, m	0x03, 0x10	0x934A	37706	Float32, CDAB
Distance Offset, m	0x03, 0x10	0x934E	37710	Float32, CDAB
Baud Rate 1200-921600	0x03, 0x10	0x924E	37454	Uint32, CDAB
RS-485 Address 1-247	0x03, 0x10	0x9301	37633	uint16, Lower 8 bits

CHAPTER 5: APPLICATION EXAMPLES

WATER TANK LEVEL MANAGEMENT (4-20 mA OUTPUT)



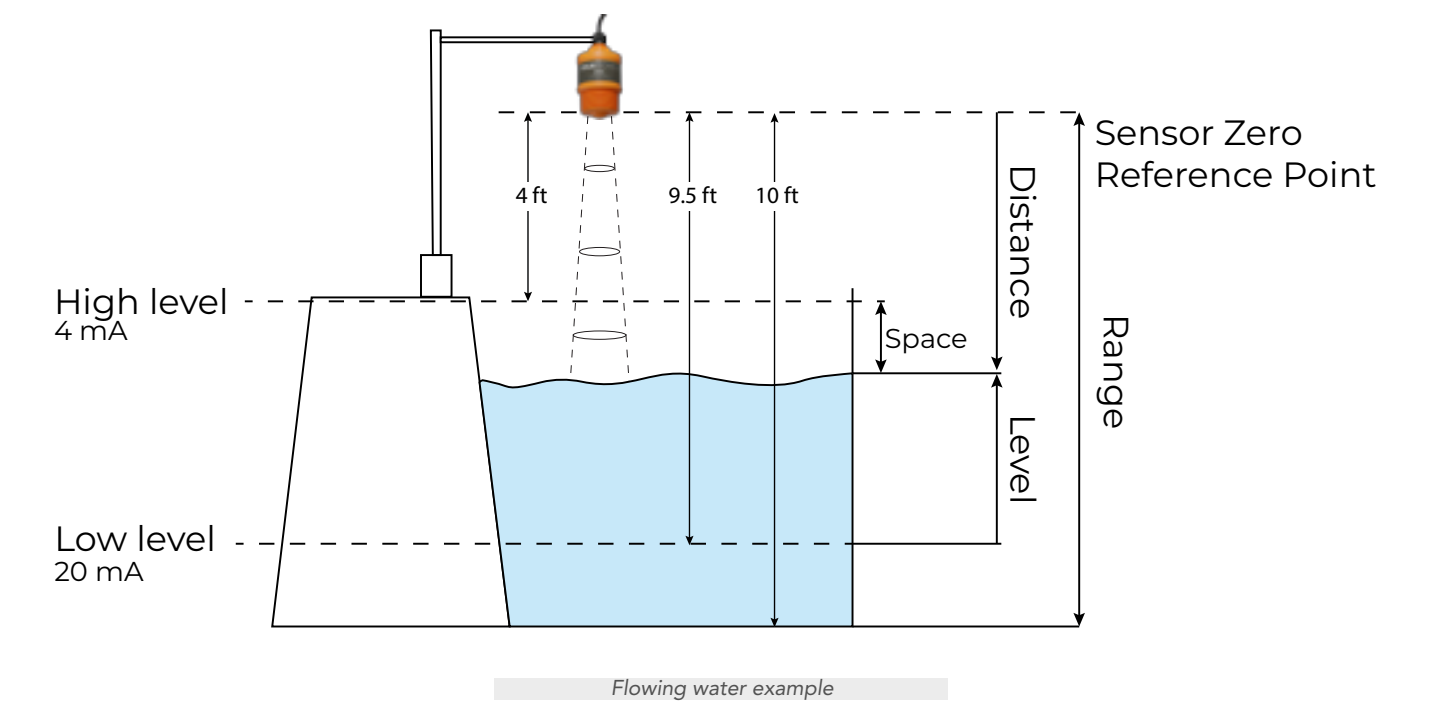
General Setup

Setting	Value	Details
Unit Setting	Ft	
Range Setting	10.5 ft (3.2 m)	Low Level
High/Low Setting		
Low Level	10.5 ft (3.2 m)	Sensor zero ref to desired lowest measured point
High Level	1.5 ft (0.46 m)	Sensor zero ref to desired highest measured point
Damping Setting	2 s	Default Value (increase if ripples cause spikes)

4-20 mA Specific Setup

Current Output		
Output Mode	4 mA Low, 20 mA High	Default Setting (4 mA at 10.5 ft [3.2 m], 20 mA at 1.5 ft [0.46 m])
Failure Mode	Hold Last Value	Default Setting

FLOWING WATER LEVEL MANAGEMENT (4-20 mA OUTPUT)



General Setup

Setting	Value	Details
Unit Setting	Ft	
Range Setting	10 ft (3 m)	Lowest Measurable Point
High/Low Setting		
Low Level	9.5 ft (2.9 m)	Sensor zero ref to desired lowest measured point
High Level	4 ft (1.2 m)	Sensor zero ref to desired highest measured point
Damping Setting	2 s	Default Value (increase if ripples cause spikes)

4-20 mA Specific Setup

Current Output		
Output Mode	20 mA Low, 4 mA High	20 mA at 9.5 ft (2.9 m), 4 mA at 4 ft (1.2 m)
Failure Mode	Hold Last Value	Default Setting

CHAPTER 6: MAINTENANCE

GENERAL CARE

Your radar is very low maintenance and will need little care as long as it is installed correctly. However, in general, you should:

- Avoid applications for which the sensor was not designed, such as extreme temperatures, contact with incompatible corrosive chemicals, or other damaging environments.
- Inspect the threads whenever you remove the sensor from duty or change its location.

APG

INTRINSICALLY SAFE APPARATUS FOR CONNECTION TO ASSOCIATED APPARATUS SPECIFIED BY ENTITY PARAMETERS



1. FOR MODEL DETAILS SEE USERS MANUAL.
2. INSTALL IN ACCORDANCE WITH SECTION 18 OF THE CEC OR ARTICLE 500 OF THE NEC.
3. THE MAXIMUM INTEGRAL CABLE LENGTH PERMITTED IS 200m AND THE INTEGRAL CABLE INDUCTANCE IS 1µH/m AND INTEGRAL CABLE CAPACITANCE IS 60pF/m.

AGENCY CONTROLLED DOCUMENT

SHEET 1 OF 1

APPENDIX B: REGULATORY WARNINGS

FCC WARNING

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions:

(1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

NOTE 1: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

NOTE 2: Any changes or modifications to this unit not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

RF Exposure Statement

To maintain compliance with FCC'S RF Exposure guidelines, This equipment should be installed and operated with minimum distance of 20cm between the radiator and your body. This device and its antenna(s) must not be co-located or operation in conjunction with any other antenna or transmitter.

ISED WARNING

This device complies with Innovation, Science and Economic Development Canada License exempt RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation of the device.

Le présent appareil est conforme aux CNR d'Innovation, Sciences et Développement économique Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes:

- (1) l'appareil n' doit pas produire de brouillage, et
- (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

The device is compliance with RF exposure guidelines, users can obtain Canadian information on RF exposure and compliance.

Le présent appareil est conforme Après examen de ce matériel aux conformité ou aux limites d'intensité de champ RF, les utilisateurs peuvent sur l'exposition aux radiofréquences et compliance d'acquérir les informations correspondantes.

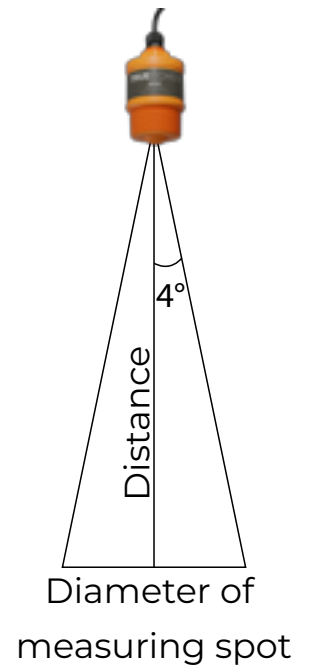
APPENDIX C: BEAM ANGLE REFERENCE TABLE

The CR-L Radar has a 4° half angle beam. The diameter of the measuring spot can be calculated using:

$$\text{Distance} * \tan(4) * 2$$

Distance (ft)	Diameter of measuring spot (ft)
1	0.140
2	0.280
4	0.559
6	0.839
8	1.119
10	1.399
12	1.678
14	1.958
16	2.238
18	2.517
20	2.797
22	3.077
24	3.356
26	3.636
28	3.916
30	4.196
32	4.475
34	4.755
36	5.035
38	5.314
40	5.594
42	5.874
44	6.154
46	6.433
48	6.713
49.213	6.883

Distance (m)	Diameter of measuring spot (m)
1	0.140
2	0.280
3	0.420
4	0.559
5	0.699
6	0.839
7	0.979
8	1.119
9	1.259
10	1.399
11	1.538
12	1.678
13	1.818
14	1.958
15	2.098





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